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Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1	1-7 (Canceled)
1 ·	8. (Currently amended): Sample observation method comprising steps of:
2	acquiring, at a first scale factor, a reference sample image not including any
3	defect on a sample with an imager, based on information on a defect on the sample detected by
4	an inspection apparatus;
5	moving the sample in a viewing field of the imager and acquiring a defective
6	sample image including the defect on the sample at a the first scale factor with the imager, based
7	on the information on the defect on the sample detected by the inspection apparatus;
8	locating the defect on the defective sample image by comparing the reference
9	sample image and the defective sample image;
10	acquiring a magnified image of the located defect at a second scale factor greater
11	than the first scale factor with the imager without moving the sample; and
12	displaying the magnified image of the defect on a screen.
1	9. (Currently amended): Sample observation method comprising the steps
2	of:
3	acquiring, at a first scale factor, a reference sample image not including any
4	defect on a sample with an imager, based on information on a defect on the sample detected by
5	an inspection apparatus;
6	adjusting a position of the sample so that the defect will fall within the field of
7	view of said imager, based on the information;
8	acquiring a defective sample image including the defect on the sample at a-the
9	first scale factor by said imager;
10	locating the defect on the defective sample image by comparing the reference
11	sample image and the defective sample image;

12	acquiring a magnified image of the located defect at a second scale factor greater
13	than the first scale factor with said imager without changing the position of the sample; and
14	displaying the magnified image of the defect on a screen.
1	10. (Previously presented): Sample observation method according to claim 9
. 2	further comprising, subsequent to the step of acquiring a magnified image, a step of:
3	erasing a background from the magnified image of the located defect.
l	11. (Previously presented): Sample observation method according to any one
2	of claims 8, 9, and 10, wherein the reference sample image and the defective sample images are
3	the images of the sample captured in secondary electrons emanated from the sample by
4	irradiation of a charged particle beam.
1	12. (Currently amended): An apparatus for observing samples, comprising:
2	image pickup means for acquiring an image of a sample;
3	storage means to store information of an area to be observed on the sample;
4	a position controller to control a position of the sample with respect to the image
5	pickup means, based on the information stored in the storage means;
6	display means to display images of the sample acquired by the image pickup
7	means; and
8	control means to locate a defect on the sample by comparing a plurality of images
9	of the sample captured by the image pickup means at a first scale factor after the sample is
10	positioned by the position controller and to control the image pickup means to acquire the a
11	located defect image at a second scale factor greater than the first scale factor without changing
12	the position of the sample-,
13	wherein the plurality of images includes a reference sample image acquired by
14	positioning the sample so that a reference area that is absent any defect is positioned within a
15	viewing field of the image pickup means,
16	wherein the plurality of images includes a defect sample image acquired by
17	positioning the sample to a defect position such that a defect area that includes at least one defect
18	is positioned within the viewing field of the image pickup means,

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19	wherein the located defect image is acquired by imaging an area of the sample
20	determined based on a comparison of the reference sample image with the defect sample image
21	without repositioning the sample from the defect position.
1	13. (Previously presented). An apparatus for observing complex comprising
2	received for observing samples, comprising
	storage means to store information on a defect on a sample detected by an
3	external defect inspection apparatus;
4	image pickup means for acquiring an image of the sample;
5	position control means to control a position of the sample, based on the
6	information stored in the storage means;
7	defect locating means to locate the defect by comparing an image of the sample
8	not including the defect and an image of the sample including the defect, wherein both of the
9	images are acquired at a first scale factor by the image pickup means after the sample is
10	positioned by the position control means; and
11	display means to display an image of the defect located by the defect locating
12	means and captured by the image pickup means at a second scale factor that is greater than the
13	first scale factor without changing the position of the sample.
1	14. (Previously presented): An apparatus for observing samples, comprising:
2	image pickup means for acquiring an image of the sample;
3	
4	position control means to control a position of the sample so that a defect on the
5	sample will fall within the field of view of the image pickup means, based on information on the
6	defect on the sample detected by an external defect inspection apparatus;
	defect locating means to locate the defect by comparing an image of the sample
7	not including the defect and an image of the sample including the defect, wherein both of the
8	images are acquired by the image pickup means at a first scale factor after the sample is
9	positioned by the position control means; and
10	display means to display an image of the defect located by the defect locating
11	means and captured by the image pickup means at a second scale factor that is greater than the
12	first scale factor without changing the position of the sample.

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1	15. (Previously presented): Sample observation equipment according to any
2	one of claims 12, 13, and 14; wherein the image pickup means is a scanning electron
3	microscope.
1	16 (7)
1	16. (Previously presented): Sample observation method according to claim 8
2	further comprising steps of:
3	moving the sample to acquire a magnified image of the reference sample with the
4	imager;
5	acquiring a magnified image of the reference sample at the second scale factor
6	with the imager; and
7	displaying the magnified image of the reference sample on the screen with the
8	magnified image of the located defect.
1	17. (Previously presented): Sample observation method according to claim 9
2	further comprising steps of:
3	
4	moving the sample to acquire a magnified image of the reference sample with the imager;
5	acquiring a magnified image of the reference sample at the second scale factor
6	with the imager; and
7	displaying the magnified image of the reference sample on the screen with the
8	magnified image of the located defect.